Policy Targeting under Network Interference

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Ex Informing farmers exposed to environmental disasters to increase insurance take-up in rural China

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How should we design information campaigns?

- \Rightarrow Choosing whom to treat:
 - (i) Researchers sampled \sim 185 villages in rural China and collected network information in these villages (Cai et al., 2015)
 - (ii) Documented spillovers in an experiment: information diffuse to friends
 - (iii) Treatment can be costly: treating each individual is sub-optimal

Suppose we collect data from experiment or quasi-experiment participants sampled from a large population

How do we *design* an allocation rule (policy function) that determines the treatment for the entire population?

Key features:

- Heterogeneity in treatment effects
- Network interference
- Treatment may be costly

Constraints may apply:

- Network information may not be observable in other villages
- Ethical, legal or computational constraints may apply

General Equilibrium Effects of Cash Transfers: Experimental Evidence from Kenya

Dennis Egger, Johannes Haushofer, Edward Miguel, Paul Niehaus & Michael W. Walker

WORKING PAPER 26600 DOI 10.3386/w26600 ISSUE DATE December 2019

How large economic stimuli generate individual and aggregate responses is a central question in economics, but han to been studied experimentally. We provided on-third cash transfers of about USD 1000 to over 10.500 poor households across 653 randomized villages in rural Kenya. The implied facul shock was over 15 percent of local GDP. We find large impacts on consumption and assets for reoipents. Importantly, we document large possible spillowers on non-recipient households and firms, and minimal price inflation. We estimate a local fiscal multiplier of 2.7. We interpret vellater implications through the lens of a simple household optimization framework.

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General Eq Exper

Price Subsidies, Diagnostic Tests, and Targeting of Malaria Treatment: Evidence from a Randomized Controlled Trial[†]

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By JESSICA COHEN, PASCALINE DUPAS, AND SIMONE SCHANER*

Both under- and over-treatment of communicable diseases are public bads. But efforts to decrease one run the risk of increasing the other. Using rich experimental data on household treatment-seeking behavior in Kenya, we study the implications of this trade-off for subsidigring iff-awing antimularital solid over-the-counter at relial drag outlets. We show that a very high subsidy (such as the one more consideration by the international community) dramatically increases access, but nearly one-half of subsidized npils go to patients without malaria. We study the vary to better target subsidized angres; reducing the subsidy level, and introducing rapid malaria tests over-the-counter (LE D12, D82, D82, 112, 012, 015).

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Published: 12 September 2012

A 61-million-person experiment in social influence and political mobilization

Robert M. Bond, Christopher J. Fariss, Jason J. Jones, Adam D. I. Kramer, Cameron Marlow, Jaime E. Settle & James H. Fowler ⊡

Nature 489, 295-298(2012) Cite this article 18k Accesses 1056 Citations 1853 Altmetric Metrics

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- RCT: collect $n_e \ll n$ individual level info
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- $D_i \in \{0, 1\}$: randomized treatment for sampled units
- $Y_i \in \mathbb{R}$: outcome of interest for sampled units
- $Z_i := (X_i, \widetilde{X}_i) \in \mathcal{Z}, X_i \in \mathcal{X}$: covariates for sampled units

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- Collect sampled units' neighbors' info
 - $\mathcal{N}_i = \{j : A_{i,j} = 1\}$: set of neighbors of each individual
 - $R_i^f = 1\{\sum_{k \in \mathcal{N}_i} R_k > 0\}$: neighbors' sampling indicator
 - $(D_{\mathcal{N}_i}, Z_{\mathcal{N}_i})$: neighbors' covariates and assignments.

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 - $(D_{\mathcal{N}_i}, Z_{\mathcal{N}_i})$: neighbors' covariates and assignments.
- \Rightarrow Construct a targeting rule (policy)

$$\pi: \mathcal{X} \mapsto \{0, 1\}, \quad \pi \in \Pi$$

that determines whom should be treated.

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 $R_i \sim_{i.i.d.} \operatorname{Bern}(n_e/n)$



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$$D_{i}|Z_{i}, R_{i}, R_{i}^{f} \sim \mathcal{P}(Z_{i}, R_{i}, R_{i}^{f})$$

$$(Y_{i}, Z_{i}, Z_{\mathcal{N}_{i}}, D_{i}, D_{\mathcal{N}_{i}})R_{i}, R_{i}]_{i=1}^{n}$$

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$$D_{i}|Z_{i}, R_{i}, R_{i}^{f} \sim \mathcal{P}(Z_{i}, R_{i}, R_{i}^{f}) \qquad \pi(X_{i})$$

$$(X_{i})_{i=1}^{n} \subseteq Z$$

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Illustrative Example

Experiment:

$$Y_i = D_i \times X_i \times \gamma_1 + \sum_{k \in \mathcal{N}_i} D_k \times \gamma_2 + \varepsilon_i.$$

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The "oracle" method maximizes the empirical welfare **Example**

$$W(\pi) = \frac{1}{n} \sum_{i=1}^{n} \Big(\pi(X_i) \times X_i \times \gamma_1 + \sum_{k \in \mathcal{N}_i} \pi(X_k) \times \gamma_2 - c \times \pi(X_i) \Big).$$

Targeting under Network Interference

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Image: Image:

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In practice (and in the paper):

- Unknown dependence with neighbors' treatments and heterogeneity
- Constraints $\pi \in \Pi$
- Policy constraints that depend on treatments in experiment D

Contributions

- Extend treatment choice literature (Manski, 2004) to spillover effects
 - Identify welfare, leveraging sampling variation as in Abadie et al., 2020
 - Semi-parametric (and cross-fitting) procedures with spillovers
 - Mixed-integer linear program formulation for optimization
- Regret analysis with interference $\sup_{\pi\in\Pi}W(\pi)-W(\hat{\pi})$
 - (Minimax) rate of convergence as function of n_e and maximum degree
 - Symmetrization for non-asymptotic regret bounds with interference + bounds on Rademacher complexity with spillovers

Main conditions

- Spillovers are local
- Policies depend on (arbitrary) individual characterics (it allows for unobserved *A*)

- Statistical Treatment Choice [E.g., Manski (2004); Kitagawa and Tetenov (2018, 2019); Athey and Wager (2021); Zhou et al. (2018); ...]
 - \Rightarrow None study the problem with interference
- Inference under interference: [E.g., Hudgens and Halloran (2008); Aronow and Samii (2017); Leung (2020); Athey et al. (2018); Savje et al. (2021); ...]
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 - \Rightarrow None study statistical treatment choice
- Welfare analysis with social interactions + Seeding [E.g., E.g., Galeotti et
 - al. (2020); Akbarpour et al. (2018); Banerjee et al. (2013); Banerjee et al. (2018); Su et
 - al. (2019); Bhattacharya et al. (2019); Graham et al. (2010); ...]
 - \Rightarrow I study choosing whom to treat as a statistical treatment choice
 - ⇒ Here, heterogeneity and constraints on policy space (+ regret analysis)

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Model and Sampling

2 Estimation and Analysis

- 3 Empirical Application
- 4 Extensions and Conclusions

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Sampling and experiment

• Pop: *n* units with fixed network A and characteristics $Z = (Z_i)_{i=1}^n$

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Sampling and experiment

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- Sampling indicators: $R_i | A, Z \sim_{i.i.d.} \text{Bern}(n_e/n)$
- Assignments:

$$D_i = f\left(Z_i, R_i, (1-R_i)1\left\{\sum_{k\in\mathcal{N}_i}R_k > 0\right\}, \varepsilon_{D_i}\right)$$

where $\varepsilon_{D_i} \sim_{i.i.d.} \mathcal{D}$ and exogenous, and f either known or unknown.

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\Rightarrow Example

- Randomly select a subset of individuals from population
- Randomize treatments to such individuals and their friends
- Treatments for the remaining units equal to baseline $D_i = 0$.
- $\Rightarrow \text{ Extension with locally dependent } R_i \text{ possible (e.g., sample small villages first)}$

Outcomes

$$Y_i = r\Big(D_i, T_i, Z_i, |\mathcal{N}_i|, \varepsilon_i\Big), \quad T_i = g_n\Big(\sum_{k \in \mathcal{N}_i} D_k, Z_i, |\mathcal{N}_i|\Big)$$

for $T_i \in \mathcal{T}_n$, $r(\cdot)$ unknown and $g_n(\cdot)$ known

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Interference

- (i) Anonymous and exogenous interference $(r(\cdot)$ is unknown)
- (ii) $g_n(\cdot)$ is exposure mapping (Aronow and Samii, 2017);
- (iii) $g_n(\cdot)$ control treatments overlap, most agnostic is $T_i = \sum_{k \in \mathcal{N}_i} D_k$

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Unobservables

- (A) Unconfoundedness: $(\varepsilon_i)_{i=1}^n \perp (\varepsilon_{D_i}, R_i)_{i=1}^n | A, Z$
- (B) Network exogeneity $\varepsilon_i | A, Z \sim \mathcal{E}_{|\mathcal{N}_i|, Z_i}$ (not necessary)
- (C) $\varepsilon_i | A, Z$ dependent for one/two-degree neighbors only E.g. $\varepsilon_i = \left(\eta_i, \sum_{k \in \mathcal{N}_i} \eta_k \right)$ for exogenous *i.i.d.* η_i

Limited (network) info: policymaker only observes a subset of covariates X_i for all i ∈ {1, · · · , n}

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- Limited (network) info: policymaker only observes a subset of covariates X_i for all i ∈ {1, · · · , n}
- Welfare: She implements policy and generates welfare

$$W_{A,Z}(\pi) = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}\left[r\left(\pi(X_i), T_i(\pi), Z_i, |N_i|, \varepsilon_i\right) \middle| A, Z\right],$$

where $T_i(\pi) = g_n \Big(\sum_{k \in \mathcal{N}_i} \pi(X_i), Z_i, |\mathcal{N}_i| \Big).$

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.

Comments

- No assumptions on X_i (might depend on network data if available)
- Welfare defn implies no carry-overs from previous experiment
- Policies $\pi(D_i, X_i) = D_i + (1 D_i)\pi(X_i)$ are possible (Appendix B)

Estimands

Defn Conditional Mean

$$m(d, t, z, l) = \mathbb{E}\Big[r(d, t, Z_i, |N_i|, \varepsilon_i)\Big|Z_i = z, |N_i| = l\Big]$$

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Defn Propensity Score:

$$e(\mathbf{d}, \mathbf{t}, \mathbf{x}, z, \mathbf{r}, l) = P(D_i, T_i = \mathbf{d}, \mathbf{t} | (Z_i, Z_{k \in N_i}, R_{k \in N_i}, |N_i|) = (z, \mathbf{x}, \mathbf{r}, l), R_i = 1)$$

 \Rightarrow Only function of marginal probabilities $P(D_i = 1 | R_i, R_i^f, Z_i)$

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Image: A matrix and a matrix

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 \Rightarrow Immediate identification strategy with sampling based uncertainty

$$W_{A,Z}(\pi) = rac{1}{n_e} \sum_{i=1}^n \mathbb{E}\left[R_i Y_i rac{I_i(\pi)}{e_i(\pi)} \Big| A, Z
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where
$$\frac{I_i(\pi)}{e_i(\pi)} = \frac{1\{D_i = \pi(X_i), T_i(\pi) = T_i\}}{e(\pi(X_i), T_i(\pi), Z_{k \in N_i}, R_{k \in N_i}, Z_i, |N_i|)}$$

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$$\frac{I_i(\pi)}{e_i(\pi)} = \frac{1\{D_i = \pi(X_i), T_i(\pi) = T_i\}}{e(\pi(X_i), T_i(\pi), Z_{k \in N_i}, R_{k \in N_i}, Z_i, |N_i|)}$$

⇒ No distributional assumptions on (A, Z) + no need of identically distributed ε_i if known propensity score

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Digression: Overlap and Network Density Matter

Asm Positive overlap on the propensity score

$$e_i(\pi) \in (\delta_n, 1 - \delta_n), \quad \text{for } \delta_n \in (0, 1), \pi \in \Pi.$$

- \Rightarrow Lack of overlap would require extrapolation
- \Rightarrow Condition depends on the support of T_i (exposure mapping)
- \Rightarrow Later we will study trimming strategies

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Asm Network cannot be "too dense",

$$\mathcal{N}_{n,\max}^{3/2}\log(\mathcal{N}_{n,\max})/(n_{\mathrm{e}}^{1/2}\delta_n)=o(1)$$

where $\mathcal{N}_{n,\max} = \max_i |\mathcal{N}_i|$.

- \Rightarrow Control dependence via largest number of connections
- ⇒ Can be relaxed using the chromatic number

1 Model and Sampling

2 Estimation and Analysis

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Estimation with known propensity score

• (Augmented) Inverse probability weighting (e.g., A&S, 2017):

$$W_n(\pi, m^c, e) = \frac{1}{n_e} \sum_{i=1}^n R_i \left(\frac{I_i(\pi)}{e_i(\pi)} (Y_i - m_i^c(\pi)) + m_i^c(\pi) \right),$$

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where $m_i^c(\pi)$ is a reg adjustment for D_i , $T_i = \pi(X_i)$, $T_i(\pi)$.

- Optimization: estimate $\hat{\pi}_{m^c,e}$ by maximizing $W_n(\pi, m^c, e)$
 - $\Rightarrow\,$ show that optimization admits a mixed-integer linear program for a large class of function classes $\Pi\,$

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Theorem 3.1

For Y_i having bounded third moment given (A, Z)

$$\mathbb{E}\left[\sup_{\pi\in\Pi} W(\pi) - W(\hat{\pi}_{m^{c},e})\right] = \mathcal{O}\left(\frac{1}{\delta_{n}}\mathcal{N}_{n,\max}\sqrt{\frac{\mathcal{N}_{n,\max}\mathrm{VC}(\Pi)\log(\mathcal{N}_{n,\max})}{n_{e}}}\right)$$

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Theorem 3.1

For Y_i having bounded third moment given (A, Z)

$$\mathbb{E}\left[\sup_{\pi\in\Pi}W(\pi)-W(\hat{\pi}_{m^{c},e})\right]=\mathcal{O}\left(\frac{1}{\delta_{n}}\mathcal{N}_{n,\max}\sqrt{\frac{\mathcal{N}_{n,\max}\mathrm{VC}(\Pi)\log(\mathcal{N}_{n,\max})}{n_{e}}}\right)$$

- No restrictions on n_e relative to n (valid for $n \gg n_e$)
- Maximum degree controls dependence and function class' complexity
 - \Rightarrow Symmetrization for non-asymptotic regret bounds under interference
 - ⇒ Upper bounds on the Rademacher complexity obtained from compositions of functions.
- Bound is informative only under "enough" sparsity
- Thm Rate in Thm 3.1 is maximin optimal with respect to n_e

- Rate characterization also depends on convergence rate of \hat{m}, \hat{e} :
 - \Rightarrow Minimax regret rate achieved with parametric estimators ($n^{-1/2}$);
- Can we improve the rate of convergence for semiparametric ones?
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- Partition sampled units into groups such that in each group two sampled units are not friends or have no shared friend
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Regret with estimation error

$$\begin{aligned} \mathcal{A}_{n} &= \frac{1}{n} \sum_{i=1}^{n} \mathbb{E} \Big[\sup_{d,s} \Big(\hat{m}_{i}(d,s,Z_{i},|N_{i}|) - m(d,s,Z_{i},|N_{i}|) \Big)^{2} \Big| R_{i} = 1, A, Z \Big] \\ \mathcal{B}_{n} &= \frac{1}{n} \sum_{i=1}^{n} \mathbb{E} \Big[\sup_{d,s} \Big(\frac{1}{\hat{e}_{i}(d,s,Z_{k\in N_{i}},Z_{i},|N_{i}|)} - \frac{1}{e(d,s,Z_{k\in N_{i}},Z_{i},|N_{i}|)} \Big)^{2} \Big| R_{i} = 1, A, Z \Big] \end{aligned}$$

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Image: A matrix and a matrix

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Theorem 3.3

For Y_i having bounded third moment given (A, Z)

$$\mathbb{E}\left[\sup_{\pi\in\Pi}W(\pi)-W(\hat{\pi}_{m^c,e})\right]=\mathcal{O}\left(\frac{1}{\delta_n}\sqrt{\frac{\mathcal{N}_{n,\max}^3\mathrm{VC}(\Pi)\log(\mathcal{N}_{n,\max})}{n_e}}+\underbrace{\sqrt{\mathcal{A}_n\mathcal{B}_n}}_{\mathrm{EstErr}_n}\right),$$

where $\operatorname{EstErr}_n = \mathcal{O}(\mathcal{N}_{n,\max}^2 n_e^{-\zeta} / \delta_n)$, and $n_e^{-\zeta}$ is convergence rate of nuisance functs on sample of i.i.d. data.

Approximate optimization

• Find (K) maximum cuts



- Estimate $\hat{\pi}_1, \hat{\pi}_2$ over each sub-graph
- Choose $\hat{\pi}_1, \hat{\pi}_2$ with largest empirical welfare on whole sample
 - \Rightarrow Exponential worst-case improvement in K for comp complexity

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Approximate Estimation

- Find K maximum cuts
- Estimate \hat{m}_i, \hat{e}_i using information from all except cut of *i*
 - \Rightarrow Same regret guarantees if K separated subgraphs exist

1 Model and Sampling

2 Estimation and Analysis

3 Empirical Application

4 Extensions and Conclusions

Davide Viviano

olicy Targeting under Network Interference

- ullet Randomly select 185 villages (from \sim 50 areas) in the experiment
- Observe network information from > 90% of participants
- $\bullet\,$ Focus on individuals for which we also observe neighbors' treatments and covariates (\sim 4000 obs)
- Less than 50% of connections are in same village, but more than 99% of connections are in same area
- Two-stage design allows tests for endogenous spillovers

Cai et al. 2015: Design



- \Rightarrow Focus on simple vs intensive session
- \Rightarrow Follow Cai et al (2015)'s main model specification, also controlling for education, rice area and risk aversion heterogeneity

Table: *Out-of-sample* welfare improvement for a classification tree upon empirical welfare-maximization targeting rule in Athey and Wager (2020) that does not account for network effects in the design of the policy.

	Educ & Rice-ar	Educ & Risk-av	Rice-ar & Risk-av	
C = 1%	0.146	0.084	0.289	
<i>C</i> = 3%	0.159	0.093	0.201	
<i>C</i> = 5%	0.093	0.111	0.143	

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Table: Estimated coefficients of the policy $\pi(X) = 1\{X^{\top}\beta + \beta_0 > 0\}$

	Rice Ar	Risk Av	Educ	Wel Impr		
				C=1%	3%	5%
NEWM	-0.068	0.395	-0.397	0.074	0.085	0.093
EWM	-0.003	-0.041	-0.473			

• Local spillovers ("information effects"):

"By varying the information available about peers' decisions and randomizing default options, we show that the network effect is driven by the diffusion of insurance knowledge rather than the purchase decisions." (Cai et al., 2015) • Local spillovers ("information effects"):

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- Maximum degree: here, $\mathcal{N}_{n,\max} \leq 5$
- Prop score: known propensity score (no need of correctly specified m(·))
- Sampling: sampling indicators independently drawn across 185 villages ⇒ unbiased welfare estimator for implementation is rural China + local dependence of R_i

- 1 Model and Sampling
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Overlap can behave poorly as the maximum degree increases.

• Issue: some nodes can have many connections ($\delta_n \approx 0$).

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• Trimming:
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Overlap can behave poorly as the maximum degree increases.

• Issue: some nodes can have many connections ($\delta_n \approx 0$).

• Trimming:
$$W(\pi) \propto W(\pi | |\mathcal{N}_i| \le \kappa_n) + \mathcal{O}(P_n(|\mathcal{N}_i| > \kappa_n))$$

 \Rightarrow Choice s.t. $P(|\mathcal{N}_i| > \kappa_n) \approx 0$

 \Rightarrow Idea: ignore the direct effect on largely connected nodes, but incorporate the spillovers that they generate.

 Non-compliance: incentive π(X_i) generates spillovers on selection into treatment.



 \Rightarrow Simple-to-estimate expression that depends on $P(S_i = 1 | \cdot)$.

 Non-compliance: incentive π(X_i) generates spillovers on selection into treatment.



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• Different target population:

- (i) reweighting mechanism for empirical welfare
- (ii) If weights are unknown, control expected regret

• Higher order dependence of order M

• Rates of convergence depend on higher order terms $\mathcal{N}_{n,\max}^{M/2}$

- I introduce a method for treatment choice with spillovers (and leverage sampling based uncertainty for policy learning)
- I derive regret guarantees for known and unknown propensity score and provide estimation and optimization procedures
- I study the method's performance in an empirical application (and simulation studies)

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Thanks! Questions? Link: dviviano.github.io/projects
Theoretical Argument

We want to bound

$$\mathcal{R}(\hat{\pi}) \leq 2\mathbb{E}\Big[\sup_{\pi\in\Pi} \Big|W(\pi) - W_n(\pi)\Big|\Big].$$

• Network interference: let $\Gamma_i = (|N_i|, Z_{k \in N_i}, Z_i, Y_i, D_i, D_{k \in N_i})$

$$\mathbb{E}\Big[\sup_{\pi\in\Pi}\Big|\frac{1}{n}\sum_{i=1}^{n}f_{\pi}(\Gamma_{i})-\mathbb{E}[f_{\pi}(\Gamma_{i})]\Big|\Big] \leq 2\mathbb{E}\Big[\sup_{\pi\in\Pi}\Big|\frac{1}{n}\sum_{i=1}^{n}\sigma_{i}f_{\pi}(\Gamma_{i})\Big|\Big] \\ \neq 2\mathbb{E}[\operatorname{Rad}_{n}(\Pi)]$$

- 1. New symmetrization argument:
 - Group individuals into group of conditionally independent units
 - Leverage sampling uncertainty R_i for symmetrization
- 2. Upper bounds on the Rademacher complexity:
 - Invoke Ledoux-Telagrand contraction inequality for spillovers;
 - Characterize the bound as a function of the square root of the maximum degree and the covering number of Π.



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